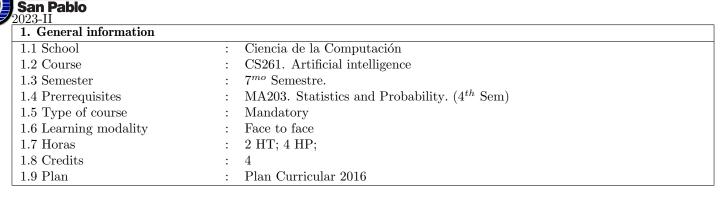
San Pablo Catholic University (UCSP) Undergraduate Program in Computer Science SILABO

CS261. Artificial intelligence (Mandatory)



2. Professors

Jniversidad Católica

Lecturer

- Juan Carlos Gutiérrez Cáceres <jcgutierrezc@ucsp.edu.pe>
 - PhD in Ciencia de la Computación, Universidad Nacional de San Agustín, Perú, 2013.
 - MSc in Ciencia de la Computación, ICMC-USP, Brasil, 2003.

3. Course foundation

Research in Artificial Intelligence has led to the development of numerous relevant tonic, aimed at the automation of human intelligence, giving a panoramic view of different algorithms that simulate the different aspects of the behavior and the intelligence of the human being.

4. Summary

1. Fundamental Issues 2. Agents 3. Basic Search Strategies 4. Advanced Search 5. Reasoning Under Uncertainty 6. Basic Machine Learning 7. Advanced Machine Learning 8. Natural Language Processing 9. Perception and Computer Vision

5. Generales Goals

- Evaluate the possibilities of simulation of intelligence, for which the techniques of knowledge modeling will be studied.
- Build a notion of intelligence that later supports the tasks of your simulation.

6. Contribution to Outcomes

This discipline contributes to the achievement of the following outcomes:

- 1) Analyze a complex computing problem and to apply principles of computing and other relevant disciplines to identify solutions. (Usage)
- 5) Function effectively as a member or leader of a team engaged in activities appropriate to the program's discipline. (Familiarity)
- 6) Apply computer science theory and software development fundamentals to produce computing-based solutions. (Familiarity)

7. Content

Competences:	
Generales Goals	
• Describe Turing test and the "Chinese Room thought experiment [Usage]	
• Determing the characteristics of a given problem	
that an intelligent systems must solve [Usage]	
-	

Competences:	
Content	Generales Goals
 Definitions of agents Agent architectures (e.g., reactive, layered, cognitive) Agent theory Rationality, game theory Decision-theoretic agents Markov decision processes (MDP) Software agents, personal assistants, and information access Collaborative agents Information-gathering agents Believable agents (synthetic characters, modeling emotions in agents) Learning agents Collaborating agents Agent teams Competitive agents (e.g., auctions, voting) Swarm systems and biologically inspired models 	 List the defining characteristics of an intelligent agent [Usage] Characterize and contrast the standard agent architectures [Usage] Describe the applications of agent theory to domain such as software agents, personal assistants, and be lievable agents [Usage] Describe the primary paradigms used by learnin agents [Usage] Demonstrate using appropriate examples how multiagent systems support agent interaction [Usage]

Readings: Nilsson (2001), Russell and Norvig (2003), Ponce-Gallegos et al. (2014)

UNIT 3: Basic Search Strategies (2)
Competences:

Competences:	
Content	Generales Goals
 Problem spaces (states, goals and operators), problem solving by search Factored representation (factoring state into variables) Uninformed search (breadth-first, depth-first, depthfirst with iterative deepening) Heuristics and informed search (hill-climbing, generic best-first, A*) Space and time efficiency of search Two-player games (introduction to minimax search) Constraint satisfaction (backtracking and local search methods) 	 Formulate an efficient problem space for a problem expressed in natural language (eg, English) in terms of initial and goal states, and operators [Usage] Describe the role of heuristics and describe the tradeoffs among completeness, optimality, time complexity, and space complexity [Usage] Describe the problem of combinatorial explosion of search space and its consequences [Usage] Compare and contrast basic search issues with game playing issues [Usage]
readings. Thisson (2001), 1 once-Ganegos et al. (2014)	

Competences:		
Content	Generales Goals	
 Stochastic search Simulated annealing Genetic algorithms Monte-Carlo tree search Constructing search trees, dynamic search space, combinatorial explosion of search space Implementation of A* search, beam search Minimax search, alpha-beta pruning Expectimax search (MDP-solving) and chance nodes 	 Design and implement a genetic algorithm solution to a problem [Usage] Design and implement a simulated annealing sched ule to avoid local minima in a problem [Usage] Design and implement A*,beam search to solve a problem [Usage] Apply minimax search with alpha-beta pruning to prune search space in a two-player game [Usage] Compare and contrast genetic algorithms with class sic search techniques [Usage] Compare and contrast various heuristic searches vis a-vis applicability to a given problem [Usage] 	

Readings: Goldberg (1989), Nilsson (2001), Russell and Norvig (2003), Ponce-Gallegos et al. (2014)

UNIT 5: Reasoning Under Uncertainty (18)	
Competences:	
Content	Generales Goals
 Review of basic probability Random variables and probability distributions Axioms of probability Probabilistic inference Bayes' Rule Conditional Independence 	 Apply Bayes' rule to determine the probability of a hypothesis given evidence [Usage] Explain how conditional independence assertions allow for greater efficiency of probabilistic systems [Usage] Identify examples of knowledge representations for reasoning under uncertainty [Usage]
 Knowledge representations – Bayesian Networks 	• State the complexity of exact inference Identify methods for approximate inference [Usage]
 * Exact inference and its complexity * Randomized sampling (Monte Carlo) methods (e.g. Gibbs sampling) – Markov Networks – Relational probability models – Hidden Markov Models 	
Readings: Koller and Friedman (2009), Russell and Norvig	(2003)

Competences:		
Content	Generales Goals	
 Definition and examples of broad variety of machine learning tasks, including classification Inductive learning Simple statistical-based learning, such as Naive Bayesian Classifier, decision trees The over-fitting problem Measuring classifier accuracy 	 List the differences among the three main styles of learning: supervised, reinforcement, and unsupervised [Usage] Identify examples of classification tasks, includin the available input features and output to be predicted [Usage] Explain the difference between inductive and deductive learning [Usage] Describe over-fitting in the context of a problem [Usage] Apply the simple statistical learning algorithm such as Naive Bayesian Classifier to a classification task and measure the classifier's accuracy [Usage] 	

Readings: Mitchell (1998), Russell and Norvig (2003), Ponce-Gallegos et al. (2014)

UNIT 7: Advanced Machine Learning (20)	
Competences:	
Content	Generales Goals
 Definition and examples of broad variety of machine learning tasks General statistical-based learning, parameter estimation (maximum likelihood) Inductive logic programming (ILP) Supervised learning Learning decision trees Learning neural networks Support vector machines (SVMs) Unsupervised Learning and clustering EM K-means Self-organizing maps Semi-supervised learning Learning graphical models Performance evaluation (such as cross-validation, area under ROC curve) Application of Machine Learning algorithms to Data Mining (cross-reference IM/Data Mining) Readings: Russell and Norvig (2003), Koller and Friedman	 Explain the differences among the three main styles of learning: supervised, reinforcement, and unsupervised [Usage] Implement simple algorithms for supervised learning, reinforcement learning, and unsupervised learning [Usage] Determine which of the three learning styles is appropriate to a particular problem domain [Usage] Compare and contrast each of the following techniques, providing examples of when each strategy is superior: decision trees, neural networks, and belief networks [Usage] Evaluate the performance of a simple learning system on a real-world dataset [Usage] Characterize the state of the art in learning theory, including its achievements and its shortcomings [Usage] Explain the problem of overfitting, along with techniques for detecting and managing the problem [Usage]
neaungs: Russen and Norvig (2005), Koner and Friedman	(2009), Mulphy (2012)

Content	Competences:	
	Generales Goals	
 Deterministic and stochastic grammars Parsing algorithms CFGs and chart parsers (e.g. CYK) Probabilistic CFGs and weighted CYK Representing meaning / Semantics Logic-based knowledge representations Semantic roles Temporal representations Beliefs, desires, and intentions Corpus-based methods N-grams and HMMs Smoothing and backoff Examples of use: POS tagging and morphology Information retrieval Vector space model * TF & IDF Precision and recall Information extraction Language translation Text classification, categorization Bag of words model 	 Define and contrast deterministic and stochasti grammars, providing examples to show the adequace of each [Usage] Simulate, apply, or implement classic and stochasti algorithms for parsing natural language [Usage] Identify the challenges of representing meaning [Us age] List the advantages of using standard corpora Identify examples of current corpora for a variety of NL tasks [Usage] Identify techniques for information retrieval, lar guage translation, and text classification [Usage] 	

Competences:	
ontent	Generales Goals
 Computer vision Image acquisition, representation, processing and properties Shape representation, object recognition and segmentation Motion analysis Modularity in recognition 	 Summarize the importance of image and object recognition in AI and indicate several significant applications of this technology [Usage] List at least three image-segmentation approache such as thresholding, edge-based and region-base algorithms, along with their defining characteristic strengths, and weaknesses [Usage] Implement 2d object recognition based on contour
• Approaches to pattern recognition	and/or region-based shape representations [Usage]
 Classification algorithms and measures of classification quality Statistical techniques 	• Provide at least two examples of a transformation a data source from one sensory domain to anothe eg, tactile data interpreted as single-band 2d imag [Usage]
	• Implement a feature-extraction algorithm on redata, eg, an edge or corner detector for images vectors of Fourier coefficients describing a short slip of audio signal [Usage]
	• Implement a classification algorithm that segmen input percepts into output categories and quantit tively evaluates the resulting classification [Usage]
	• Evaluate the performance of the underlying featur extraction, relative to at least one alternative po sible approach (whether implemented or not) in i contribution to the classification task (8), above [U age]

Readings: Nilsson (2001), Russell and Norvig (2003), Ponce-Gallegos et al. (2014)

- 8. Methodology
- 1. El profesor del curso presentará clases teóricas de los temas señalados en el programa propiciando la intervención de los alumnos.
- $2. \ {\rm El}$ profesor del curso presentará demostraciones para fundamentar clases teóricas.
- 3. El profesor y los alumnos realizarán prácticas
- 4. Los alumnos deberán asistir a clase habiendo leído lo que el profesor va a presentar. De esta manera se facilitará la comprensión y los estudiantes estarán en mejores condiciones de hacer consultas en clase.

9. Assessment

Continuous Assessment 1 : 20 %

Partial Exam : 30~%

Continuous Assessment 2 : 20~%

Final exam : 30%

References

De Castro, L.N. (2006). Fundamentals of natural computing: basic concepts, algorithms, and applications. CRC Press. Goldberg, David (1989). Genetic Algorithms in Search, Optimization and Machine Learning. Addison Wesley. Koller, Daphne and Nir Friedman (2009). Probabilistic Graphical Models: Principles and Techniques - Adaptive Computa-

tion and Machine Learning. The MIT Press. ISBN: 0262013193.

Mitchell, M. (1998). An introduction to genetic algorithms. The MIT press.

Murphy, Kevin P. (2012). Machine Learning: A Probabilistic Perspective. The MIT Press. ISBN: 0262018020.

Nilsson, Nils (2001). Inteligencia Artificial: Una nueva visión. McGraw-Hill.

Ponce-Gallegos, Julio et al. (2014). Inteligencia Artificial. Iniciativa Latinoamericana de Libros de Texto Abiertos (LATIn). Russell, Stuart and Peter Norvig (2003). Inteligencia Artifical: Un enfoque moderno. Prentice Hall.