

**San Pablo Catholic University (UCSP)**  
**Undergraduate Program in**  
**Computer Science**  
**SILABO**



**CS251. Computer graphics (Mandatory)**

**1. General information**

1.1 School	:	Ciencia de la Computación
1.2 Course	:	CS251. Computer graphics
1.3 Semester	:	7 <sup>mo</sup> Semestre.
1.4 Prerequisites	:	<ul style="list-style-type: none"><li>• CS312. Advanced Data Structures . (6<sup>th</sup> Sem)</li><li>• MA306. Numerical Analysis. (5<sup>th</sup> Sem)</li></ul>
1.5 Type of course	:	Mandatory
1.6 Learning modality	:	Virtual
1.7 Horas	:	2 HT; 2 HP; 2 HL;
1.8 Credits	:	4

**2. Professors**

**Lecturer**

- Manuel Loaiza Fernandez <meloaza@ucsp.edu.pe>
  - PhD in Informatica, Pontificia Universidad Católica do Rio de Janeiro (PUC-RIO), Brasil, 2009.
  - MSc in Informatica, Pontificia Universidad Católica do Rio de Janeiro (PUC-RIO), Brasil, 2005.

**3. Course foundation**

It offers an introduction to the area of Computer Graphics, which is an important part of Computer Science. The purpose of this course is to investigate the fundamental principles, techniques and tools for this area.

**4. Summary**

1. Fundamental Concepts 2. Basic Rendering 3. Programming Interactive Systems 4. Geometric Modeling 5. Advanced Rendering 6. Computer Animation

**5. Generales Goals**

- Bring students to concepts and techniques used in complex 3-D graphics applications.
- Give the student the necessary tools to determine which graphics software and which platform are best suited to develop a specific application.

**6. Contribution to Outcomes**

This discipline contributes to the achievement of the following outcomes:

- a) An ability to apply knowledge of mathematics, science. (**Usage**)
- b) An ability to design and conduct experiments, as well as to analyze and interpret data. (**Usage**)
- i) An ability to use the techniques, skills, and modern computing tools necessary for computing practice. (**Usage**)
- j) Apply the mathematical basis, principles of algorithms and the theory of Computer Science in the modeling and design of computational systems in such a way as to demonstrate understanding of the equilibrium points involved in the chosen option. (**Usage**)

## 7. Content

### UNIT 1: Fundamental Concepts (6)

Competences: a,b

#### Content

- Media applications including user interfaces, audio and video editing, game engines, cad, visualization, virtual reality
- Tradeoffs between storing data and re-computing data as embodied by vector and raster representations of images
- Additive and subtractive color models (CMYK and RGB) and why these provide a range of colors
- Animation as a sequence of still images

#### Generales Goals

- Explain in general terms how analog signals can be reasonably represented by discrete samples, for example, how images can be represented by pixels [Familiarity]
- Describe color models and their use in graphics display devices [Familiarity]
- Describe the tradeoffs between storing information vs storing enough information to reproduce the information, as in the difference between vector and raster rendering [Familiarity]
- Describe the basic process of producing continuous motion from a sequence of discrete frames (sometimes called “flicker fusion”) [Familiarity]

**Readings:** Hearn and Baker (1990)

<b>UNIT 2: Basic Rendering (12)</b>	
<b>Competences: a,b,i</b>	
<b>Content</b>	<b>Generales Goals</b>
<ul style="list-style-type: none"> <li>• Rendering in nature, e.g., the emission and scattering of light and its relation to numerical integration</li> <li>• Forward and backward rendering (i.e., ray-casting and rasterization)</li> <li>• Basic radiometry, similar triangles, and projection model</li> <li>• Affine and coordinate system transformations</li> <li>• Ray tracing</li> <li>• Visibility and occlusion, including solutions to this problem such as depth buffering, Painter’s algorithm, and ray tracing</li> <li>• Simple triangle rasterization</li> <li>• Rendering with a shader-based API</li> <li>• Application of spatial data structures to rendering</li> <li>• Sampling and anti-aliasing</li> <li>• Forward and backward rendering (i.e., ray-casting and rasterization)</li> </ul>	<ul style="list-style-type: none"> <li>• Discuss the light transport problem and its relation to numerical integration ie, light is emitted, scatters around the scene, and is measured by the eye [Familiarity]</li> <li>• Describe the basic graphics pipeline and how forward and backward rendering factor in this [Familiarity]</li> <li>• Create a program to display 3D models of simple graphics images [Usage]</li> <li>• Obtain 2-dimensional and 3-dimensional points by applying affine transformations [Usage]</li> <li>• Apply 3-dimensional coordinate system and the changes required to extend 2D transformation operations to handle transformations in 3D [Usage]</li> <li>• Contrast forward and backward rendering [Assessment]</li> <li>• Explain the concept and applications of texture mapping, sampling, and anti-aliasing [Familiarity]</li> <li>• Explain the ray tracing/rasterization duality for the visibility problem [Familiarity]</li> <li>• Implement a simple real-time renderer using a rasterization API (eg, OpenGL) using vertex buffers and shaders [Usage]</li> <li>• Compute space requirements based on resolution and color coding [Assessment]</li> <li>• Compute time requirements based on refresh rates, rasterization techniques [Assessment]</li> </ul>
<b>Readings:</b> Hearn and Baker (1990), Hughes et al. (2013), Wolff (2011), Shreiner et al. (2013)	

<b>UNIT 3: Programming Interactive Systems (2)</b>	
<b>Competences: a,b</b>	
<b>Content</b>	<b>Generales Goals</b>
<ul style="list-style-type: none"> <li>• Event management and user interaction</li> <li>• Approaches to design, implementation and evaluation of non-mouse interaction <ul style="list-style-type: none"> <li>– Touch and multi-touch interfaces</li> <li>– Shared, embodied, and large interfaces</li> <li>– New input modalities (such as sensor and location data)</li> <li>– New Windows, e.g., iPhone, Android</li> <li>– Speech recognition and natural language processing</li> <li>– Wearable and tangible interfaces</li> <li>– Persuasive interaction and emotion</li> <li>– Ubiquitous and context-aware interaction technologies (UbiComp)</li> <li>– Bayesian inference (e.g. predictive text, guided pointing)</li> <li>– Ambient/peripheral display and interaction</li> </ul> </li> </ul>	<ul style="list-style-type: none"> <li>• Discuss the advantages (and disadvantages) of non-mouse interfaces [Assessment]</li> </ul>
<b>Readings:</b> Hearn and Baker (1990)	

<b>UNIT 4: Geometric Modeling (15)</b>	
<b>Competences: a,b,i,j</b>	
<b>Content</b>	<b>Generales Goals</b>
<ul style="list-style-type: none"> <li>• Basic geometric operations such as intersection calculation and proximity tests</li> <li>• Volumes, voxels, and point-based representations</li> <li>• Parametric polynomial curves and surfaces</li> <li>• Implicit representation of curves and surfaces</li> <li>• Approximation techniques such as polynomial curves, Bezier curves, spline curves and surfaces, and nonuniform rational basis (NURB) spines, and level set method</li> <li>• Surface representation techniques including tessellation, mesh representation, mesh fairing, and mesh generation techniques such as Delaunay triangulation, marching cubes</li> <li>• Spatial subdivision techniques</li> <li>• Procedural models such as fractals, generative modeling, and L-systems</li> <li>• Elastically deformable and freeform deformable models</li> <li>• Subdivision surfaces</li> <li>• Multiresolution modeling</li> <li>• Reconstruction</li> <li>• Constructive Solid Geometry (CSG) representation</li> </ul>	<ul style="list-style-type: none"> <li>• Represent curves and surfaces using both implicit and parametric forms [Usage]</li> <li>• Create simple polyhedral models by surface tessellation [Usage]</li> <li>• Generate a mesh representation from an implicit surface [Usage]</li> <li>• Generate a mesh from data points acquired with a laser scanner [Usage]</li> <li>• Construct CSG models from simple primitives, such as cubes and quadric surfaces [Usage]</li> <li>• Contrast modeling approaches with respect to space and time complexity and quality of image [Assessment]</li> </ul>
<b>Readings:</b> Hearn and Baker (1990), Shreiner et al. (2013)	

<b>UNIT 5: Advanced Rendering (6)</b>	
<b>Competences: a,b,i</b>	
<b>Content</b>	<b>Generales Goals</b>
<ul style="list-style-type: none"> <li>• Time (motion blur), lens position (focus), and continuous frequency (color) and their impact on rendering</li> <li>• Shadow mapping</li> <li>• Occlusion culling</li> <li>• Subsurface scattering</li> <li>• Non-photorealistic rendering</li> <li>• GPU architecture</li> <li>• Human visual systems including adaptation to light, sensitivity to noise, and flicker fusion</li> </ul>	<ul style="list-style-type: none"> <li>• Demonstrate how an algorithm estimates a solution to the rendering equation [Assessment]</li> <li>• Prove the properties of a rendering algorithm, eg, complete, consistent, and unbiased [Assessment]</li> <li>• Implement a non-trivial shading algorithm (eg, toon shading, cascaded shadow maps) under a rasterization API [Usage]</li> <li>• Discuss how a particular artistic technique might be implemented in a renderer [Familiarity]</li> <li>• Explain how to recognize the graphics techniques used to create a particular image [Familiarity]</li> </ul>
<b>Readings:</b> Hearn and Baker (1990), Hughes et al. (2013), Wolff (2011), Shreiner et al. (2013)	

UNIT 6: Computer Animation (4)	
Competences: a,b,i,j	
Content	Generales Goals
<ul style="list-style-type: none"> <li>• Forward and inverse kinematics</li> <li>• Collision detection and response</li> <li>• Procedural animation using noise, rules (boids/crowds), and particle systems</li> <li>• Skinning algorithms</li> <li>• Physics based motions including rigid body dynamics, physical particle systems, mass-spring networks for cloth and flesh and hair</li> <li>• Key-frame animation</li> <li>• Splines</li> <li>• Data structures for rotations, such as quaternions</li> <li>• Camera animation</li> <li>• Motion capture</li> </ul>	<ul style="list-style-type: none"> <li>• Compute the location and orientation of model parts using an forward kinematic approach [Usage]</li> <li>• Implement the spline interpolation method for producing in-between positions and orientations [Usage]</li> <li>• Implement algorithms for physical modeling of particle dynamics using simple Newtonian mechanics, for example Witkin &amp; Kass, snakes and worms, symplectic Euler, Stormer/Verlet, or midpoint Euler methods [Usage]</li> <li>• Discuss the basic ideas behind some methods for fluid dynamics for modeling ballistic trajectories, for example for splashes, dust, fire, or smoke [Familiarity]</li> <li>• Use common animation software to construct simple organic forms using metaball and skeleton [Usage]</li> </ul>
<b>Readings:</b> Hearn and Baker (1990), Shreiner et al. (2013)	

8. Methodology
<p>El profesor del curso presentará clases teóricas de los temas señalados en el programa propiciando la intervención de los alumnos.</p> <p>El profesor del curso presentará demostraciones para fundamentar clases teóricas.</p> <p>El profesor y los alumnos realizarán prácticas</p> <p>Los alumnos deberán asistir a clase habiendo leído lo que el profesor va a presentar. De esta manera se facilitará la comprensión y los estudiantes estarán en mejores condiciones de hacer consultas en clase.</p>

9. Assessment
<p><b>Continuous Assessment 1</b> : 20 %</p> <p><b>Partial Exam</b> : 30 %</p> <p><b>Continuous Assessment 2</b> : 20 %</p> <p><b>Final exam</b> : 30 %</p>

## References

Hearn, Donald and Pauline Baker (1990). *Computer Graphics in C*. Prentice Hall.

Hughes, John F. et al. (2013). *Computer Graphics - Principles and Practice 3rd Edition*. Addison-Wesley.

Shreiner, Dave et al. (2013). *OpenGL, Programming Guide, Eighth Edition*. Addison-Wesley.

Wolff, David (2011). *OpenGL 4.0 Shading Language Cookbook*. Packt Publishing.